

## **Data-Intensive Distributed Computing**

CS 451/651 431/631 (Winter 2018)

Part 3: Analyzing Text (2/2) January 30, 2018

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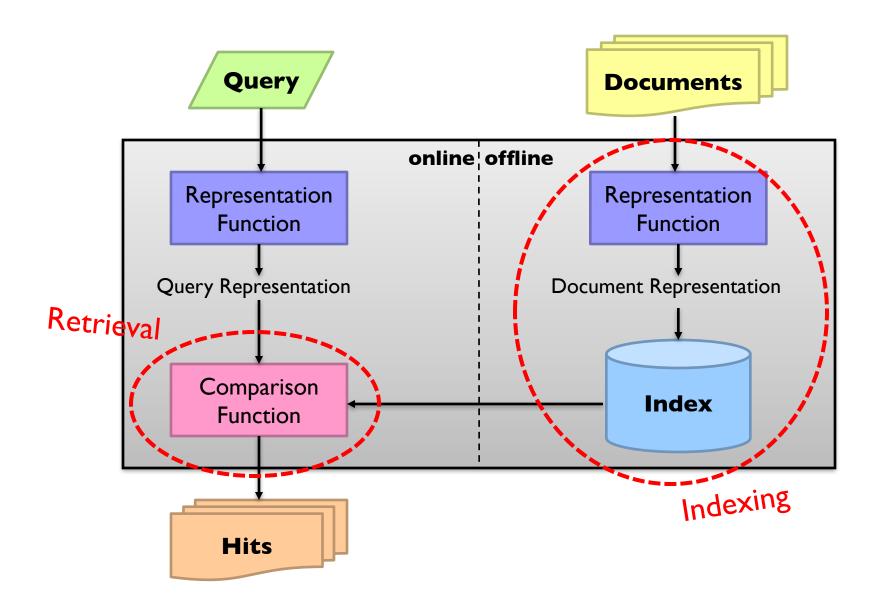
University of Waterloo

These slides are available at http://lintool.github.io/bigdata-2018w/





## Abstract IR Architecture

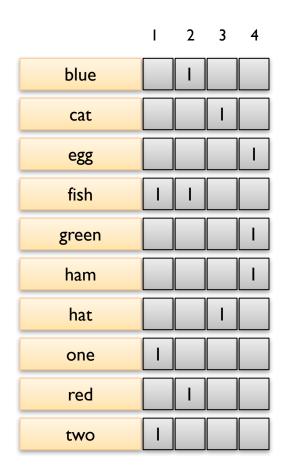


Doc 1

Doc 2

Doc 3

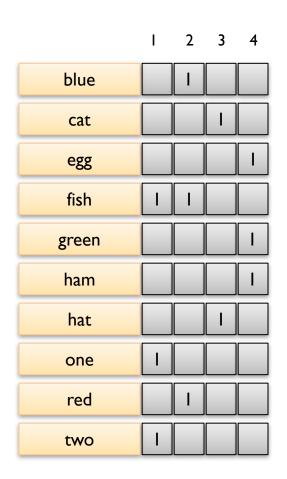
Doc 4 one fish, two fish red fish, blue fish cat in the hat green eggs and ham



What goes in each cell?

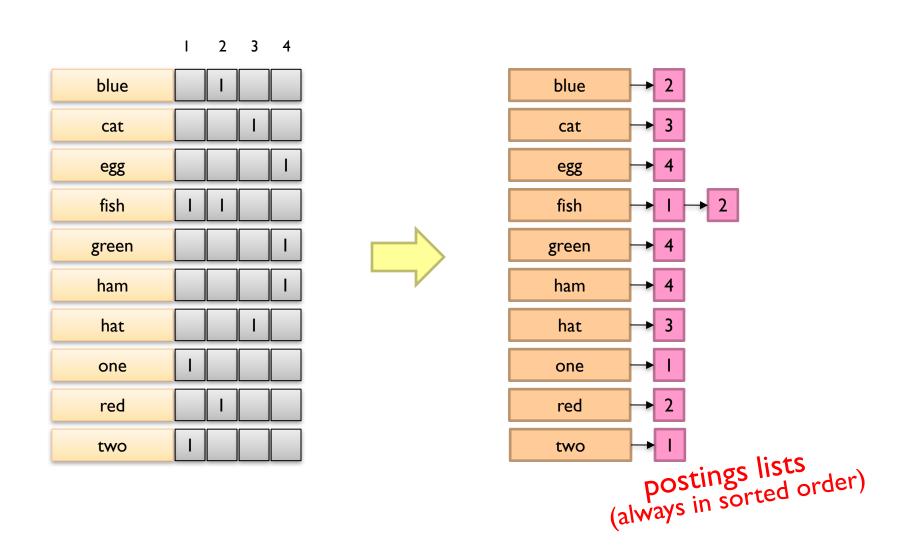
boolean count positions

Doc 1 Doc 2 Doc 3 Doc 4 one fish, two fish red fish, blue fish cat in the hat green eggs and ham

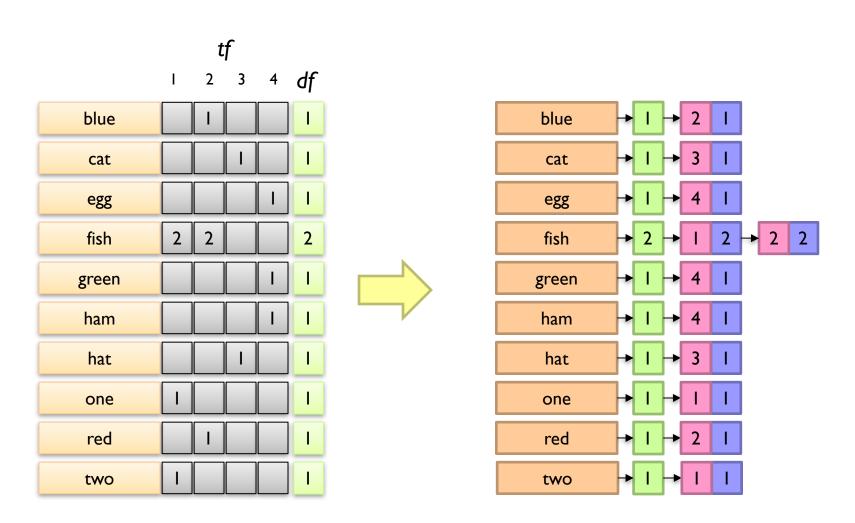


Indexing: building this structure
Retrieval: manipulating this structure

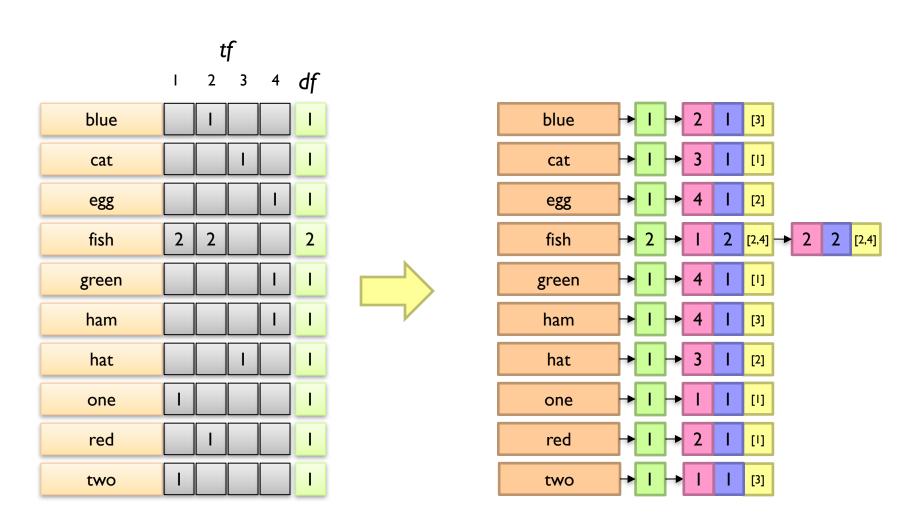
Doc 1 Doc 2 Doc 3 Doc 4 one fish, two fish red fish, blue fish cat in the hat green eggs and ham



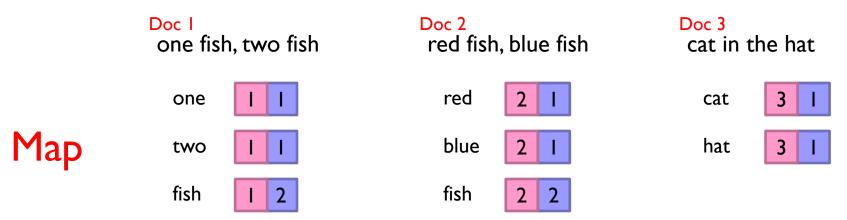
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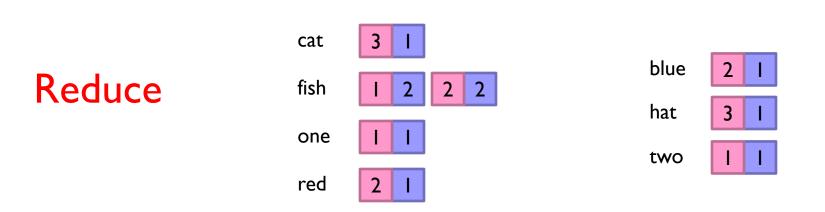
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# Inverted Indexing with MapReduce



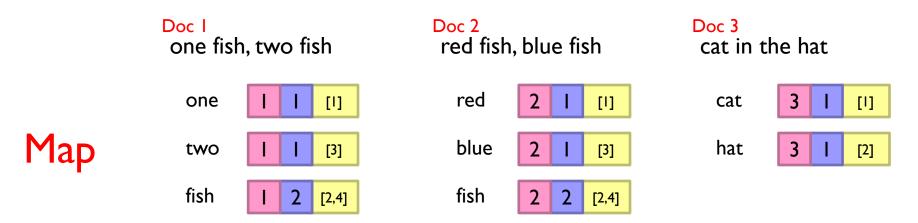
#### Shuffle and Sort: aggregate values by keys



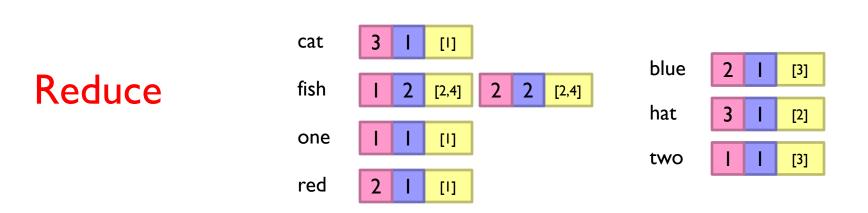
## Inverted Indexing: Pseudo-Code

```
class Mapper {
  def map(docid: Long, doc: String) = {
    val counts = new Map()
    for (term <- tokenize(doc)) {</pre>
      counts(term) += 1
    for ((term, tf) <- counts) {
      emit(term, (docid, tf))
class Reducer {
  def reduce(term: String, postings: Iterable[(docid, tf)]) = {
    val p = new List()
    for ((docid, tf) <- postings) {
      p.append((docid, tf))
    p.sort()
    emit(term, p)
```

### Positional Indexes



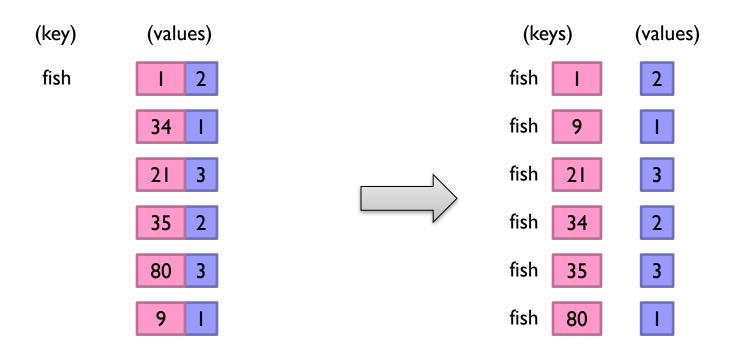
#### Shuffle and Sort: aggregate values by keys



## Inverted Indexing: Pseudo-Code

```
class Mapper {
  def map(docid: Long, doc: String) = {
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    for (term <- tokenize(doc)) {</pre>
      counts(term) += 1
    for ((term, tf) <- counts) {
      emit(term, (docid, tf))
class Reducer {
  def reduce(term: String, postings: Iterable[(docid, tf)]) = {
    val p = new List()
    for ((docid, tf) <- postings) {
   p.append((docid, tf)) What's the problem?
    p.sort()
    emit(term, p)
```

## Another Try...



How is this different?

Let the framework do the sorting!

Where have we seen this before?

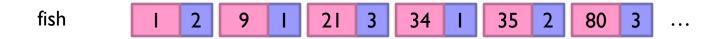
# Inverted Indexing: Pseudo-Code

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class Mapper {
  def map(docid: Long, doc: String) = {
    val counts = new Map()
    for (term <- tokenize(doc)) {</pre>
      counts(term) += 1
    for ((term, tf) <- counts) {
      emit((term, docid), tf)
class Reducer {
 var prev = null
 val postings = new PostingsList()
  def reduce(key: Pair, tf: Iterable[Int]) = {
    if key.term != prev and prev != null {
      emit(prev, postings)
      postings.reset()
                                Wait, how's this any better?
   postings.append(key.docid, tf.first)
def cleanup() = {
   emit(prev, postings)
```

What else do we need to do?

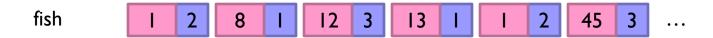
# Postings Encoding

### Conceptually:



#### In Practice:

Don't encode docids, encode gaps (or *d*-gaps) But it's not obvious that this save space...



= delta encoding, delta compression, gap compression

## Overview of Integer Compression

Byte-aligned technique VByte

Bit-aligned
Unary codes  $\gamma/\delta$  codes
Golomb codes (local Bernoulli model)

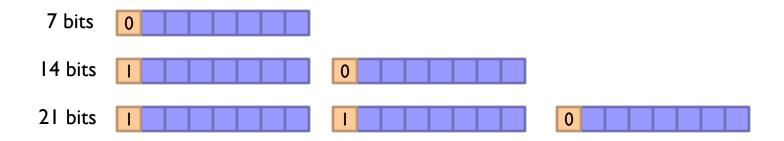
Word-aligned

Simple family
Bit packing family (PForDelta, etc.)

## **VByte**

Simple idea: use only as many bytes as needed

Need to reserve one bit per byte as the "continuation bit" Use remaining bits for encoding value

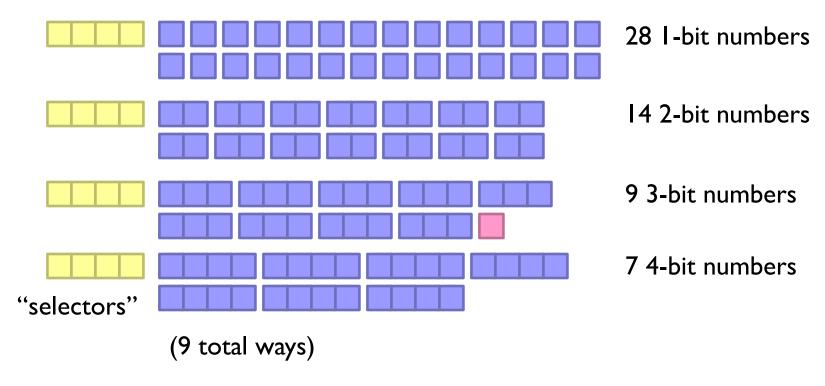


Works okay, easy to implement...

Beware of branch mispredicts!

## Simple-9

How many different ways can we divide up 28 bits?

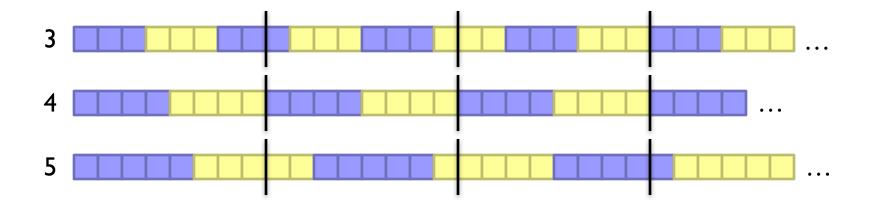


Efficient decompression with hard-coded decoders Simple Family – general idea applies to 64-bit words, etc.

Beware of branch mispredicts?

## Bit Packing

What's the smallest number of bits we need to code a block (=128) of integers?



Efficient decompression with hard-coded decoders

PForDelta – bit packing + separate storage of "overflow" bits

Beware of branch mispredicts?

## Golomb Codes

### $x \ge 1$ , parameter *b*:

```
q + 1 in unary, where q = \lfloor (x - 1)/b \rfloor
r in binary, where r = x - qb - 1, in \lfloor \log b \rfloor or \lceil \log b \rceil bits
```

### Example:

$$b = 3$$
,  $r = 0$ , 1, 2 (0, 10, 11)  
 $b = 6$ ,  $r = 0$ , 1, 2, 3, 4, 5 (00, 01, 100, 101, 110, 111)  
 $x = 9$ ,  $b = 3$ :  $q = 2$ ,  $r = 2$ , code = 110:11  
 $x = 9$ ,  $b = 6$ :  $q = 1$ ,  $r = 2$ , code = 10:100

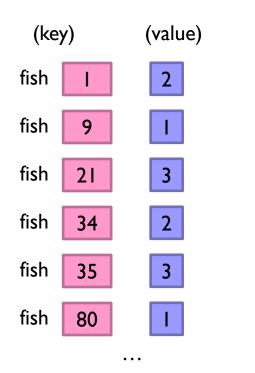
Punch line: optimal  $b \sim 0.69 (N/df)$ 

Different b for every term!

# Inverted Indexing: Pseudo-Code

```
class Mapper {
  def map(docid: Long, doc: String) = {
   val counts = new Map()
   for (term <- tokenize(doc)) {</pre>
      counts(term) += 1
   for ((term, tf) <- counts) {
      emit((term, docid), tf)
class Reducer {
 var prev = null
 val postings = new PostingsList()
 def reduce(key: Pair, tf: Iterable[Int]) = {
    if key.term != prev and prev != null {
      emit(prev, postings)
      postings.reset()
                        Ah, now we know why this is different!
   postings.append(key.docid, tf.first)
def cleanup() = {
   emit(prev, postings)
```

## Chicken and Egg?



But wait! How do we set the Golomb parameter *b*?

Recall: optimal  $b \sim 0.69 (N/df)$ 

We need the df to set b...

But we don't know the *df* until we've seen all postings!

Write postings compressed

## Getting the df

### In the mapper:

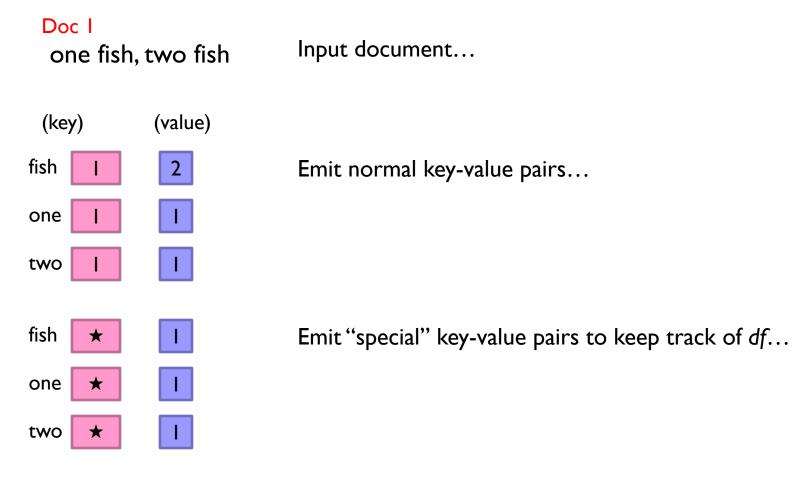
Emit "special" key-value pairs to keep track of df

### In the reducer:

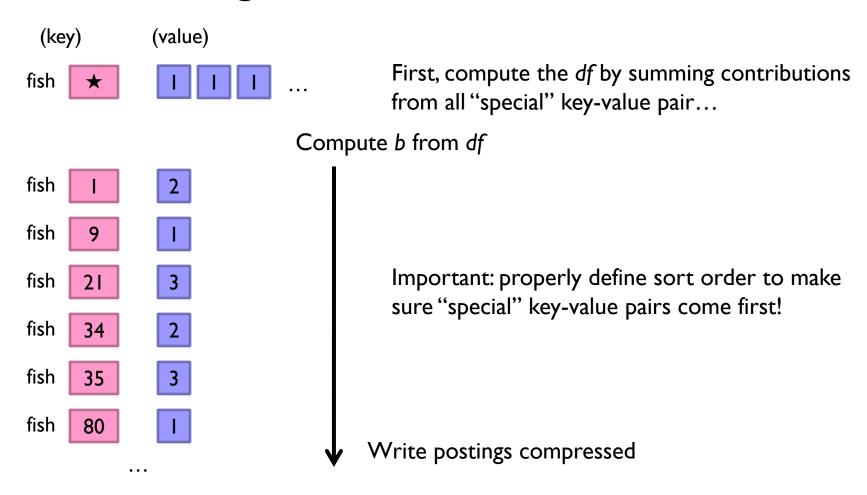
Make sure "special" key-value pairs come first: process them to determine df

Remember: proper partitioning!

# Getting the df: Modified Mapper

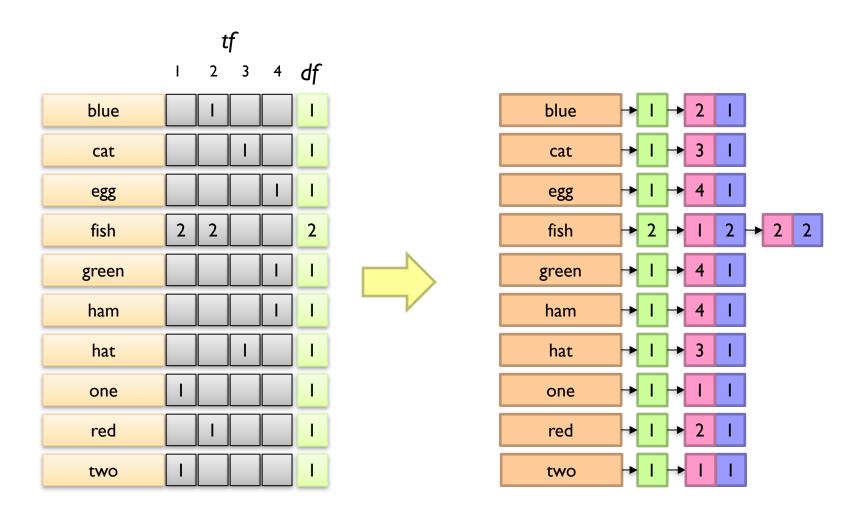


# Getting the df: Modified Reducer

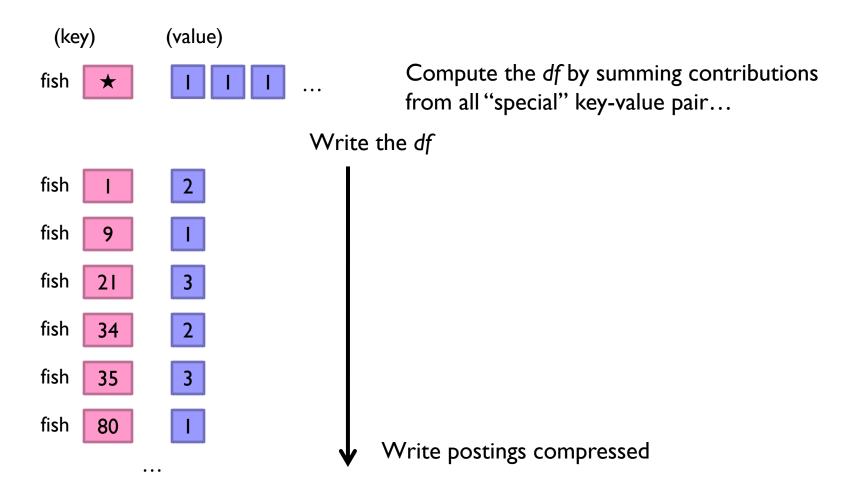


Where have we seen this before?

### But I don't care about Golomb Codes!



## Basic Inverted Indexer: Reducer



# Inverted Indexing: IP (~Pairs)

```
class Mapper {
 def map(docid: Long, doc: String) = {
   val counts = new Map()
   for (term <- tokenize(doc)) {</pre>
     counts(term) += 1
   for ((term, tf) <- counts) {
     emit((term, docid), tf)
class Reducer {
 var prev = null
 val postings = new PostingsList()
 def reduce(key: Pair, tf: Iterable[Int]) = {
   if key.term != prev and prev != null {
  emit(key.term, postings)
def cleanup() = {
  emit(prev, postings)
```

# Merging Postings

Let's define an operation ⊕ on postings lists *P*:

```
Postings(I, I5, 22, 39, 54) 

Postings(2, 46) 

Postings(1, 2, I5, 22, 39, 46, 54)
```

What exactly is this operation?
What have we created?

Then we can rewrite our indexing algorithm!

## What's the issue?

Postings<sub>1</sub> ⊕ Postings<sub>2</sub> = Postings<sub>M</sub>

Solution: apply compression as needed!

# Inverted Indexing: LP (~Stripes)

Slightly less elegant implementation... but uses same idea

```
class Mapper {
  val m = new Map()
  def map(docid: Long, doc: String) = {
    val counts = new Map()
    for (term <- tokenize(doc)) {</pre>
      counts(term) += 1
    for ((term, tf) <- counts) {</pre>
      m(term).append((docid, tf))
    if memoryFull()
      flush()
  def cleanup() = {
    flush()
  def flush() = {
    for (term <- m.keys) {</pre>
                                     What's happening here?
      emit(term, new PostingsList(m(term)))
    m.clear()
```

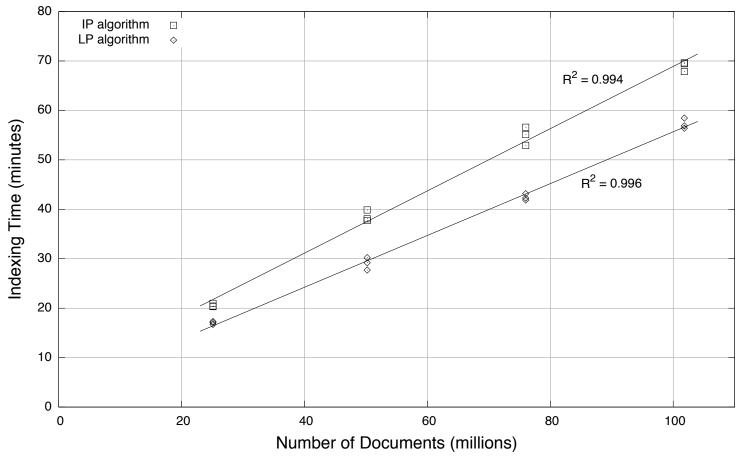
# Inverted Indexing: LP (~Stripes)

```
class Reducer {
  def reduce(term: String, lists: Iterable[PostingsList]) = {
    var f = new PostingsList()

    for (list <- lists) {
        f = f + list
        }
        What's happening here!
    }
    emit(term, f)
}</pre>
```

## LP vs. IP?

Experiments on ClueWeb09 collection: segments 1 + 2 101.8m documents (472 GB compressed, 2.97 TB uncompressed)

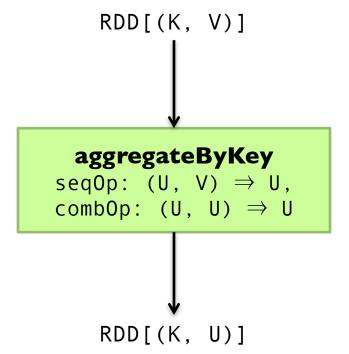


Alg.	Time	Intermediate Pairs	Intermediate Size
IP	38.5 min	$13 \times 10^{9}$	$306 \times 10^9$ bytes
LP	29.6 min	$614 \times 10^{6}$	$85 \times 10^9$ bytes

## Another Look at LP

```
class Mapper {
                                             flatMap: emit singleton postings
  val m = new Map()
                                                        reduceByKey: ⊕
  def map(docid: Long, doc: String) = {
    val counts = new Map()
    for (term <- tokenize(doc)) {</pre>
      counts(term) += 1
    for ((term, tf) <- counts) {</pre>
      m(term).append((docid, tf))
    if memoryFull()
      flush()
  }
  def cleanup() = {
    flush()
  def flush() = {
    for (term <- m.keys) {</pre>
      emit(term, new PostingsList(m(term)))
    m.clear()
}
class Reducer {
  def reduce(term: String, lists: Iterable[PostingsList]) = {
    val f = new PostingsList()
    for (list <- lists) {</pre>
      f = f + list
    emit(term, f)
```

# Remind you of anything in Spark?



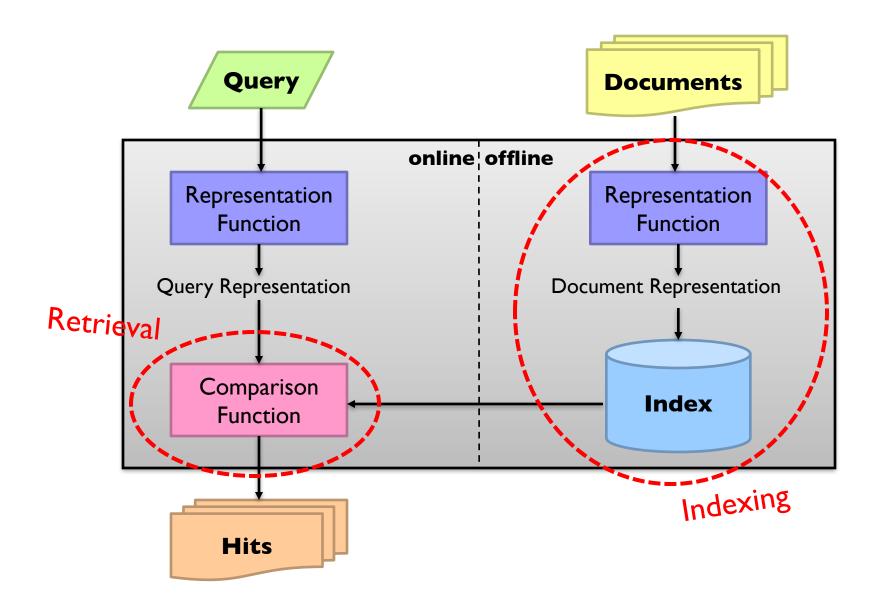


Exploit associativity and commutativity via commutative monoids (if you can)

Exploit framework-based sorting to sequence computations (if you can't)

Source: Wikipedia (Walnut)

## Abstract IR Architecture



## MapReduce it?

## Perfect for MapReduce!

Scalability is critical

Must be relatively fast, but need not be real time

Fundamentally a batch operation

Incremental updates may or may not be important

For the web, crawling is a challenge in itself

#### The retrieval problem

Must have sub-second response time For the web, only need relatively few results

Uh... not so good...



#### Boolean Retrieval

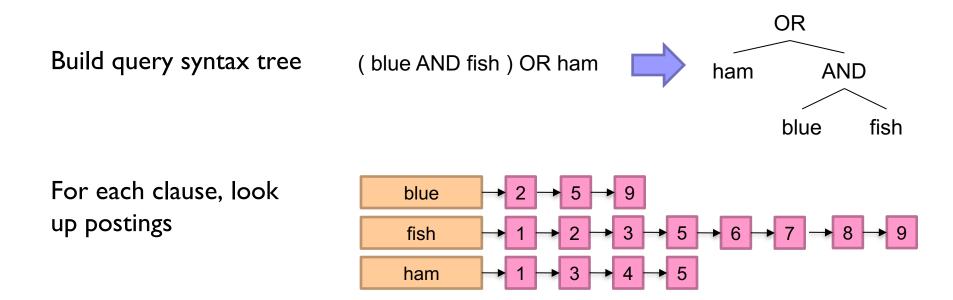
Users express queries as a Boolean expression AND, OR, NOT Can be arbitrarily nested

Retrieval is based on the notion of sets

Any query divides the collection into two sets: retrieved, not-retrieved Pure Boolean systems do not define an ordering of the results

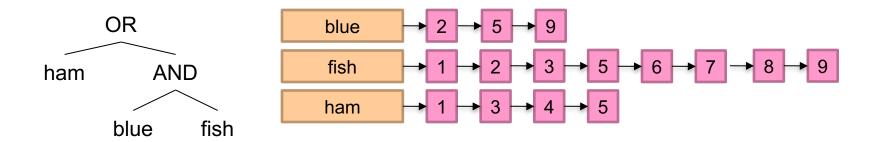
#### Boolean Retrieval

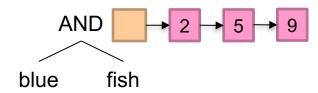
To execute a Boolean query:



Traverse postings and apply Boolean operator

#### Term-at-a-Time





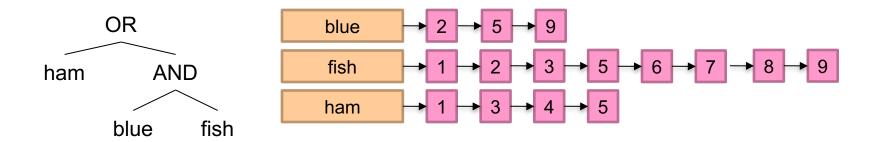
fish

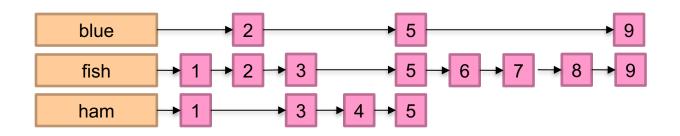
blue

OR 1 2 3 4 5 9
ham AND

Efficiency analysis?

#### Document-at-a-Time





Tradeoffs?
Efficiency analysis?

#### Boolean Retrieval

# Users express queries as a Boolean expression AND, OR, NOT Can be arbitrarily nested

#### Retrieval is based on the notion of sets

Any query divides the collection into two sets: retrieved, not-retrieved Pure Boolean systems do not define an ordering of the results

What's the issue?

#### Ranked Retrieval

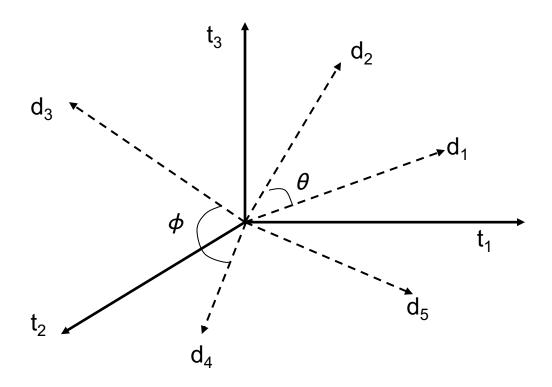
Order documents by how likely they are to be relevant

Estimate relevance  $(q, d_i)$ Sort documents by relevance

How do we estimate relevance?

Take "similarity" as a proxy for relevance

## Vector Space Model



Assumption: Documents that are "close together" in vector space "talk about" the same things

Therefore, retrieve documents based on how close the document is to the query (i.e., similarity ~ "closeness")

## Similarity Metric

Use "angle" between the vectors:

$$d_{j} = [w_{j,1}, w_{j,2}, w_{j,3}, \dots w_{j,n}]$$

$$d_{k} = [w_{k,1}, w_{k,2}, w_{k,3}, \dots w_{k,n}]$$

$$\cos \theta = \frac{d_{j} \cdot d_{k}}{|d_{j}| |d_{k}|}$$

$$sim(d_j, d_k) = \frac{d_j \cdot d_k}{|d_j||d_k|} = \frac{\sum_{i=0}^n w_{j,i} w_{k,i}}{\sqrt{\sum_{i=0}^n w_{j,i}^2} \sqrt{\sum_{i=0}^n w_{k,i}^2}}$$

Or, more generally, inner products:

$$sim(d_j, d_k) = d_j \cdot d_k = \sum_{i=0}^{n} w_{j,i} w_{k,i}$$

## Term Weighting

#### Term weights consist of two components

Local: how important is the term in this document? Global: how important is the term in the collection?

#### Here's the intuition:

Terms that appear often in a document should get high weights Terms that appear in many documents should get low weights

How do we capture this mathematically?

Term frequency (local)
Inverse document frequency (global)

## TF.IDF Term Weighting

$$w_{i,j} = \mathrm{tf}_{i,j} \cdot \log \frac{N}{n_i}$$

 $W_{i,j}$  weight assigned to term i in document j

 $\operatorname{tf}_{i,\,j}$  number of occurrence of term i in document j

N number of documents in entire collection

 $n_i$  number of documents with term i

#### Retrieval in a Nutshell

Look up postings lists corresponding to query terms

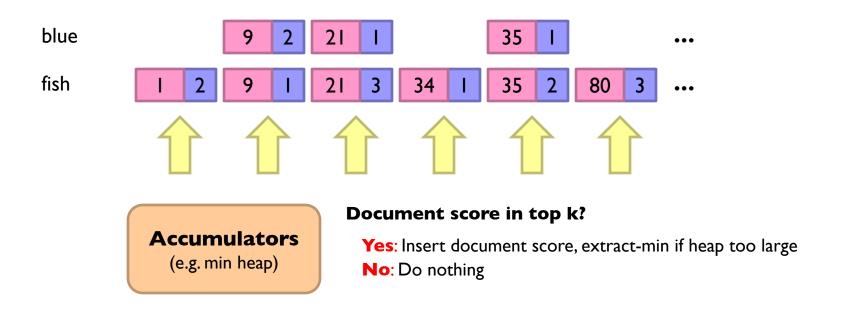
Traverse postings for each query term

Store partial query-document scores in accumulators

Select top k results to return

#### Retrieval: Document-at-a-Time

Evaluate documents one at a time (score all query terms)



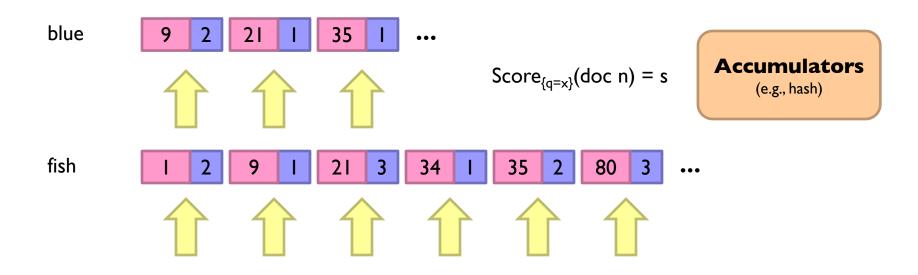
#### Tradeoffs:

Small memory footprint (good)
Skipping possible to avoid reading all postings (good)
More seeks and irregular data accesses (bad)

#### Retrieval: Term-At-A-Time

Evaluate documents one query term at a time

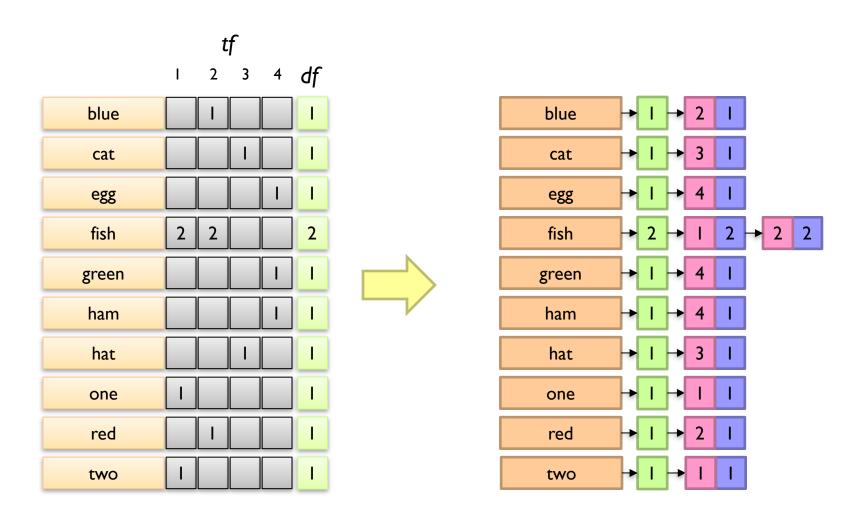
Usually, starting from most rare term (often with tf-sorted postings)



#### Tradeoffs:

Early termination heuristics (good)
Large memory footprint (bad), but filtering heuristics possible

## Why store df as part of postings?



Assume everything fits in memory on a single machine... Okay, let's relax this assumption now

## Important Ideas

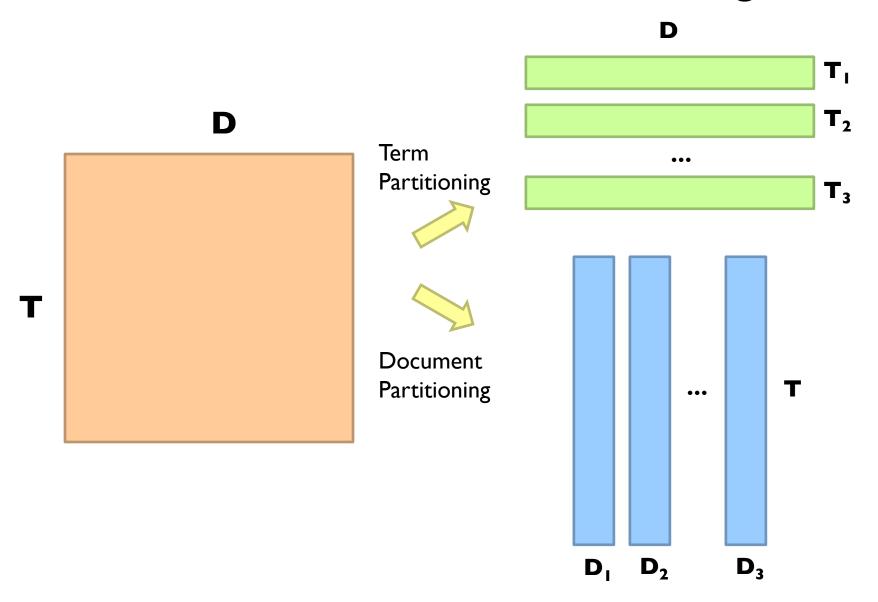
Partitioning (for scalability)

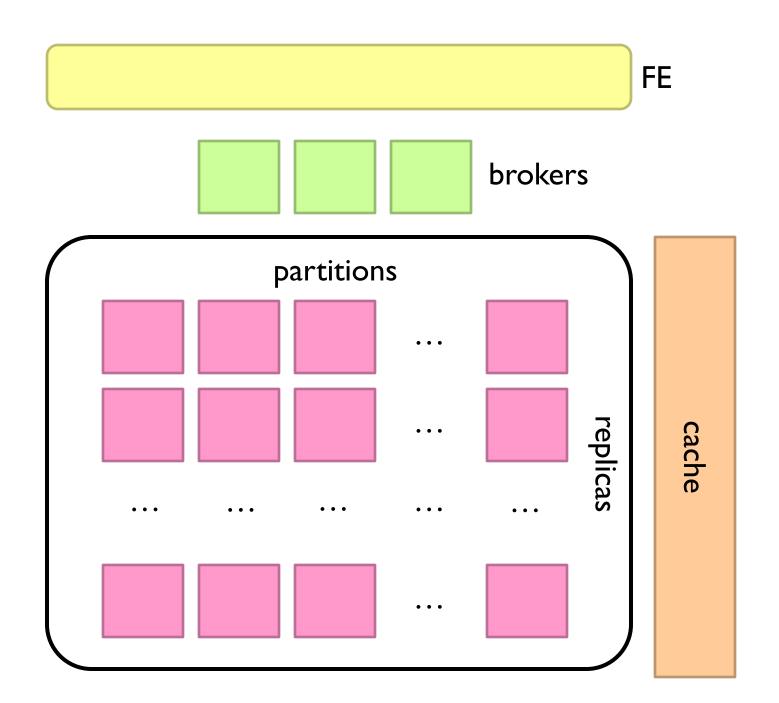
Replication (for redundancy)

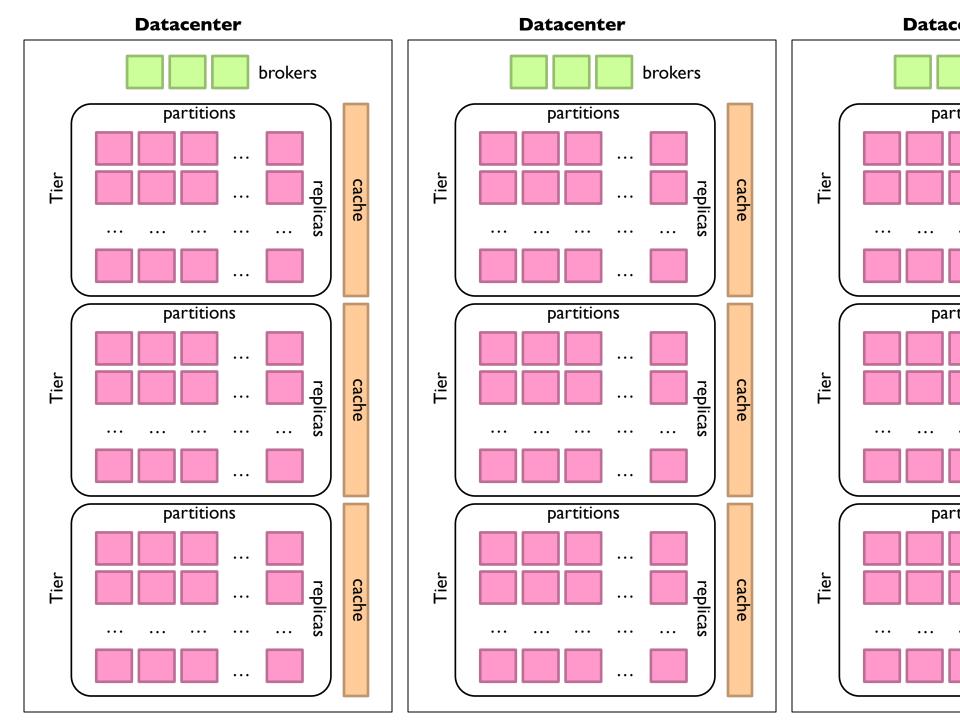
Caching (for speed)

Routing (for load balancing)

## Term vs. Document Partitioning







## Important Ideas

Partitioning (for scalability)

Replication (for redundancy)

Caching (for speed)

Routing (for load balancing)

