

Data-Intensive Information Processing Applications — Session #5

Graph Algorithms



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Source: Wikipedia (Japanese rock garden)

Today's Agenda

- Graph problems and representations
- Parallel breadth-first search
- PageRank

What's a graph?

- $G = (V, E)$, where
 - V represents the set of vertices (nodes)
 - E represents the set of edges (links)
 - Both vertices and edges may contain additional information
- Different types of graphs:
 - Directed vs. undirected edges
 - Presence or absence of cycles
- Graphs are everywhere:
 - Hyperlink structure of the Web
 - Physical structure of computers on the Internet
 - Interstate highway system
 - Social networks

Some Graph Problems

- Finding shortest paths
 - Routing Internet traffic and UPS trucks
- Finding minimum spanning trees
 - Telco laying down fiber
- Finding Max Flow
 - Airline scheduling
- Identify “special” nodes and communities
 - Breaking up terrorist cells, spread of avian flu
- Bipartite matching
 - Monster.com, Match.com
- And of course... PageRank

Graphs and MapReduce

- Graph algorithms typically involve:
 - Performing computations at each node: based on node features, edge features, and local link structure
 - Propagating computations: “traversing” the graph
- Key questions:
 - How do you represent graph data in MapReduce?
 - How do you traverse a graph in MapReduce?

Representing Graphs

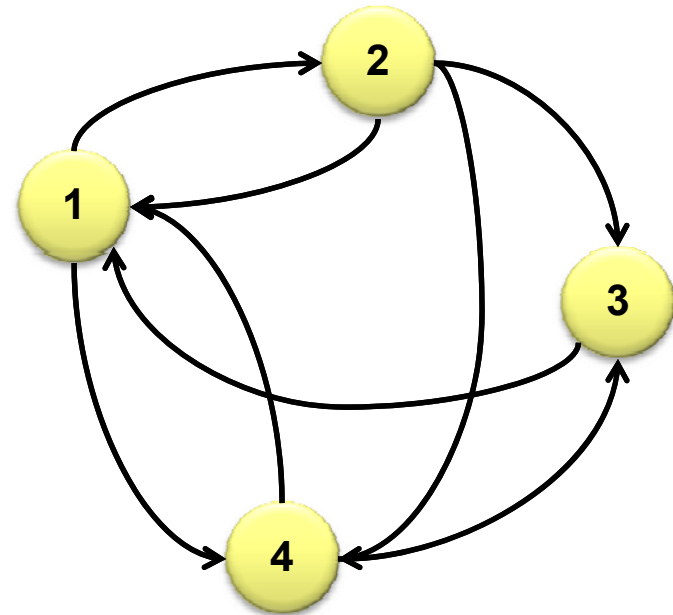
- $G = (V, E)$
- Two common representations
 - Adjacency matrix
 - Adjacency list

Adjacency Matrices

Represent a graph as an $n \times n$ square matrix M

- $n = |V|$
- $M_{ij} = 1$ means a link from node i to j

	1	2	3	4
1	0	1	0	1
2	1	0	1	1
3	1	0	0	0
4	1	0	1	0



Adjacency Matrices: Critique

- Advantages:

- Amenable to mathematical manipulation
- Iteration over rows and columns corresponds to computations on outlinks and inlinks

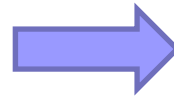
- Disadvantages:

- Lots of zeros for sparse matrices
- Lots of wasted space

Adjacency Lists

Take adjacency matrices... and throw away all the zeros

	1	2	3	4
1	0	1	0	1
2	1	0	1	1
3	1	0	0	0
4	1	0	1	0



1: 2, 4
2: 1, 3, 4
3: 1
4: 1, 3

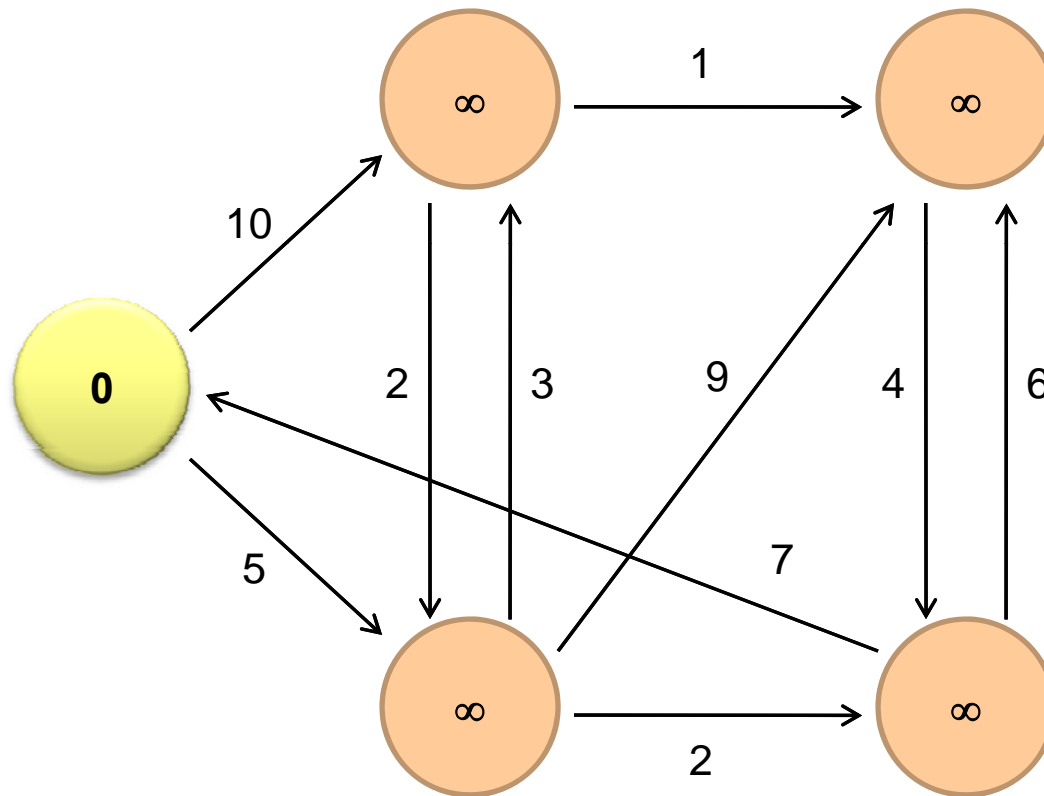
Adjacency Lists: Critique

- Advantages:
 - Much more compact representation
 - Easy to compute over outlinks
- Disadvantages:
 - Much more difficult to compute over inlinks

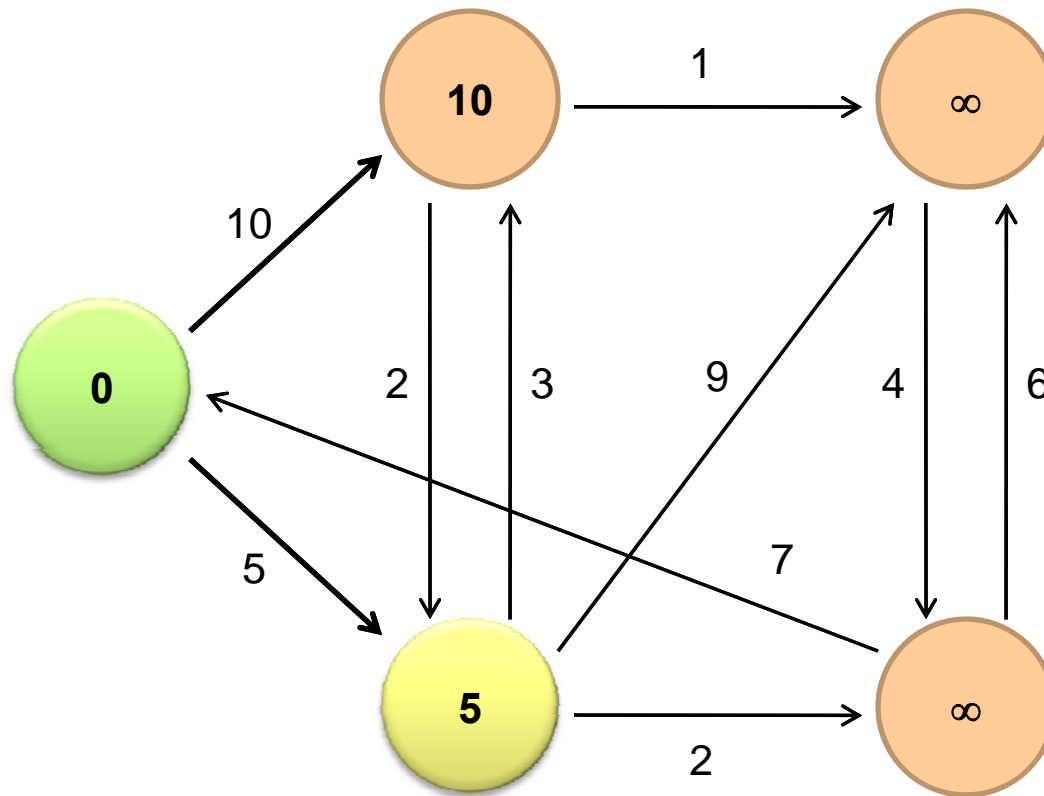
Single Source Shortest Path

- **Problem:** find shortest path from a source node to one or more target nodes
 - Shortest might also mean lowest weight or cost
- First, a refresher: Dijkstra's Algorithm

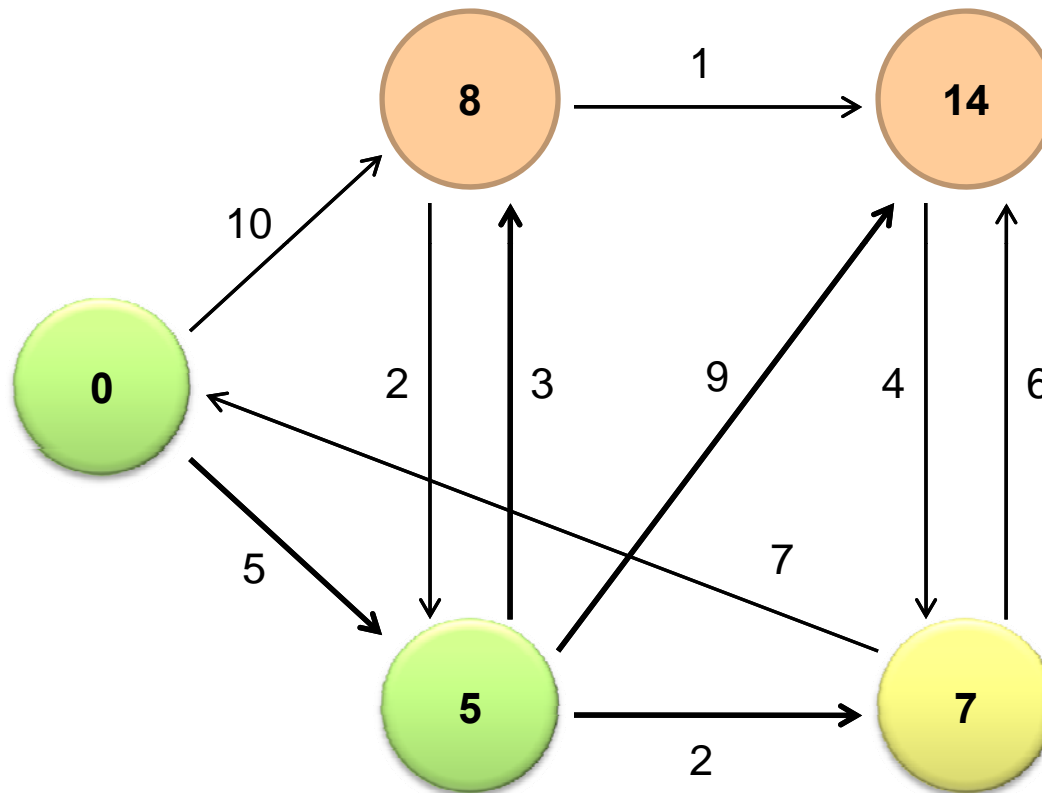
Dijkstra's Algorithm Example



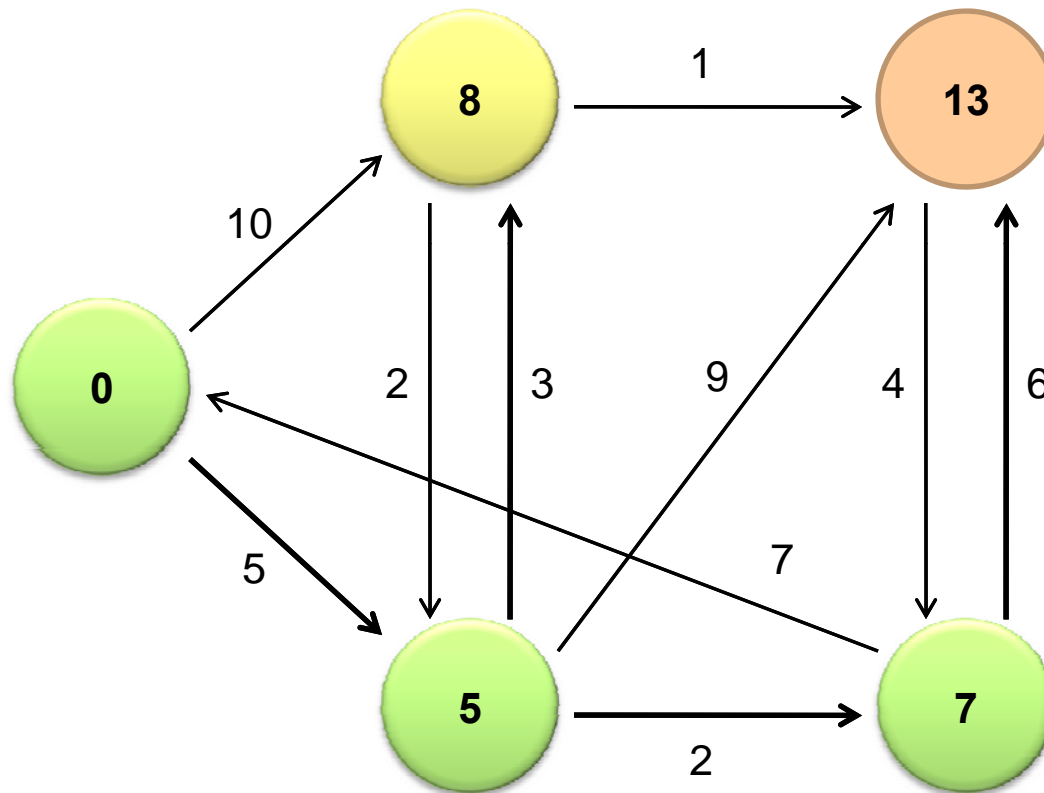
Dijkstra's Algorithm Example



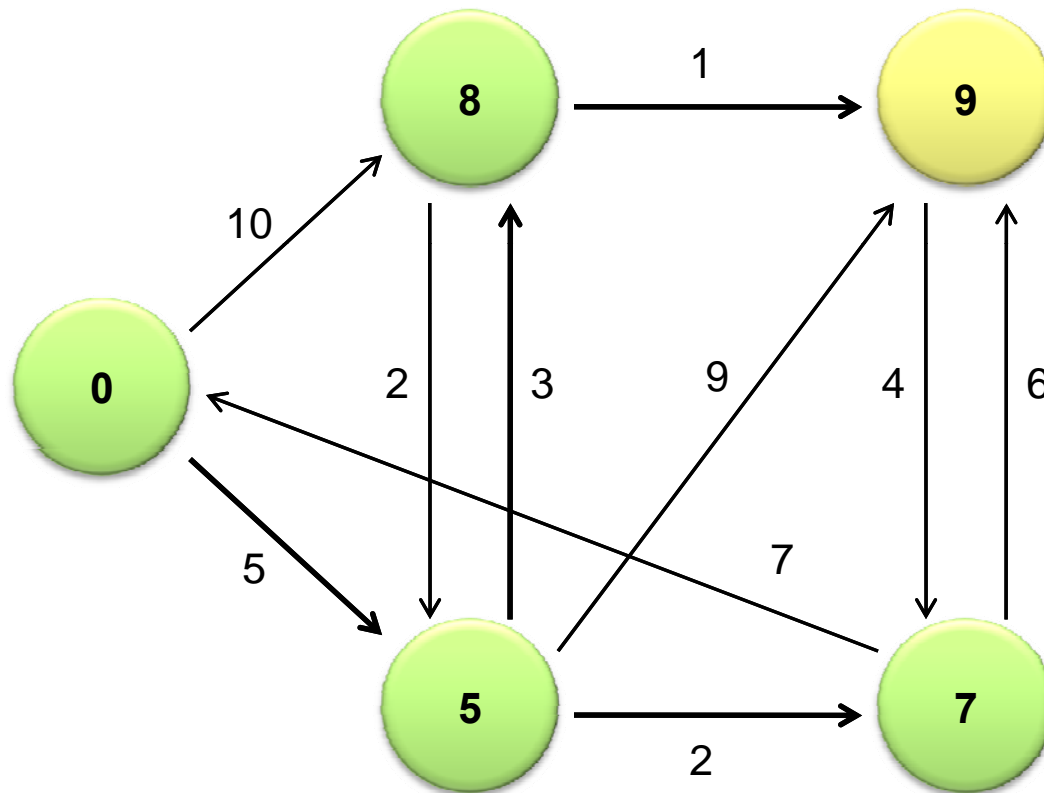
Dijkstra's Algorithm Example



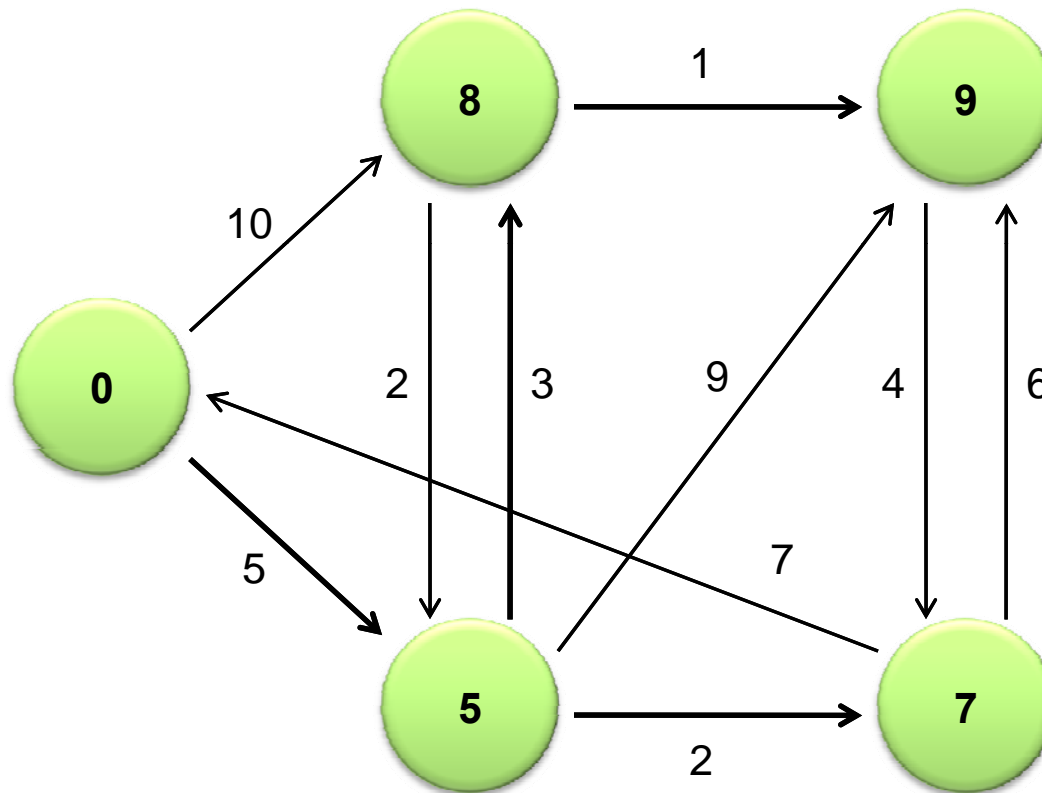
Dijkstra's Algorithm Example



Dijkstra's Algorithm Example



Dijkstra's Algorithm Example

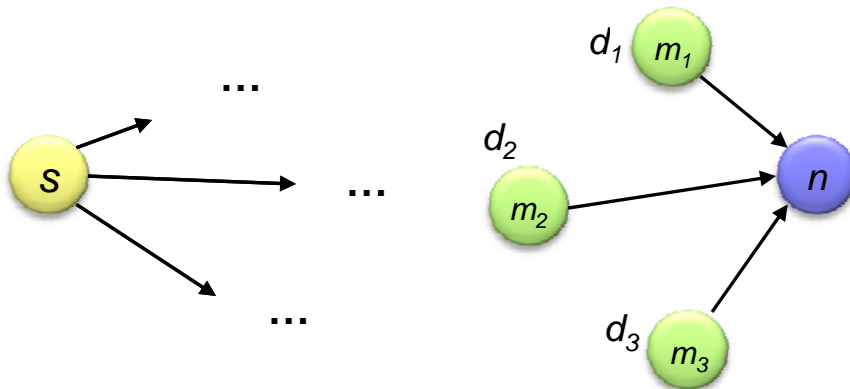


Single Source Shortest Path

- **Problem:** find shortest path from a source node to one or more target nodes
 - Shortest might also mean lowest weight or cost
- Single processor machine: Dijkstra's Algorithm
- MapReduce: parallel Breadth-First Search (BFS)

Finding the Shortest Path

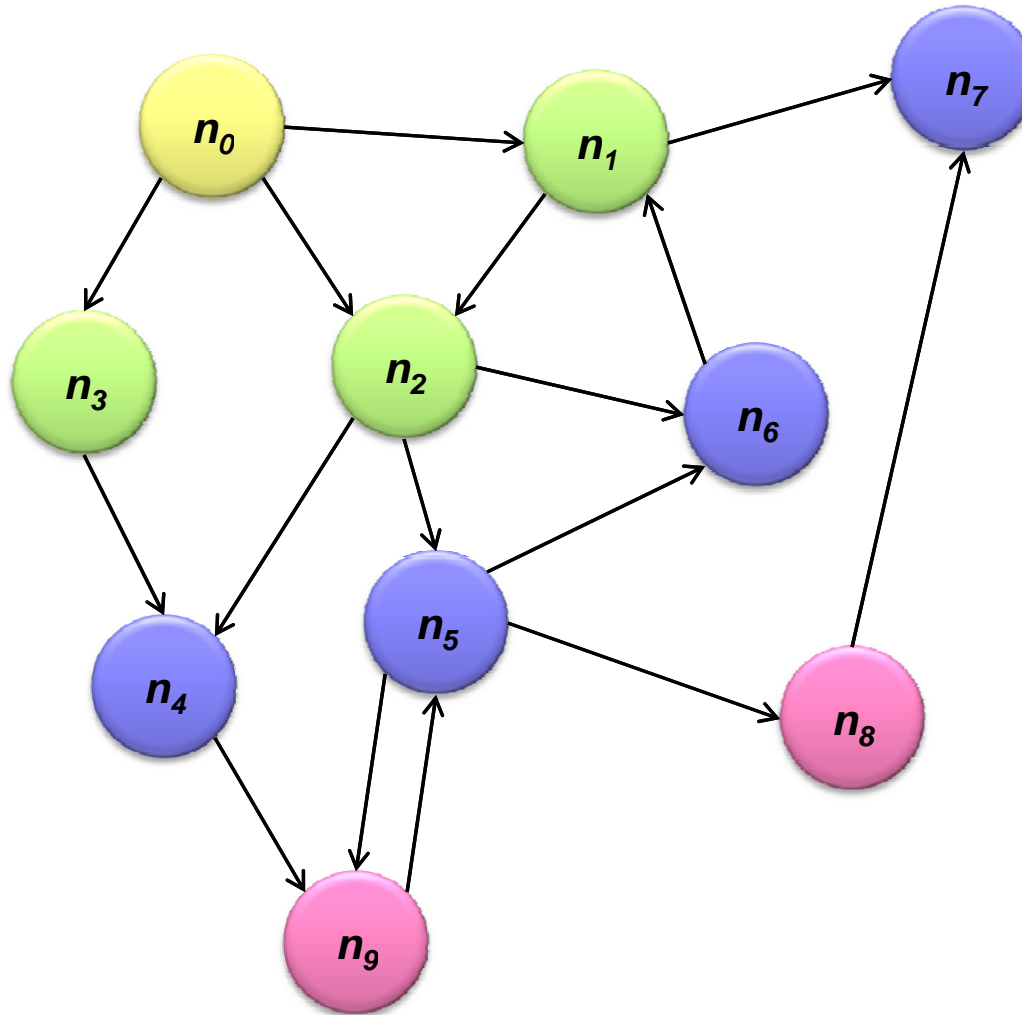
- Consider simple case of equal edge weights
- Solution to the problem can be defined inductively
- Here's the intuition:
 - Define: b is reachable from a if b is on adjacency list of a
 - $\text{DISTANCETO}(s) = 0$
 - For all nodes p reachable from s ,
 $\text{DISTANCETO}(p) = 1$
 - For all nodes n reachable from some other set of nodes M ,
 $\text{DISTANCETO}(n) = 1 + \min(\text{DISTANCETO}(m), m \in M)$





Source: Wikipedia (Wave)

Visualizing Parallel BFS



From Intuition to Algorithm

- Data representation:
 - Key: node n
 - Value: d (distance from start), adjacency list (list of nodes reachable from n)
 - Initialization: for all nodes except for start node, $d = \infty$
- Mapper:
 - $\forall m \in \text{adjacency list: emit } (m, d + 1)$
- Sort/Shuffle
 - Groups distances by reachable nodes
- Reducer:
 - Selects minimum distance path for each reachable node
 - Additional bookkeeping needed to keep track of actual path

Multiple Iterations Needed

- Each MapReduce iteration advances the “known frontier” by one hop
 - Subsequent iterations include more and more reachable nodes as frontier expands
 - Multiple iterations are needed to explore entire graph
- Preserving graph structure:
 - Problem: Where did the adjacency list go?
 - Solution: mapper emits (n , adjacency list) as well

BFS Pseudo-Code

```
1: class MAPPER
2:   method MAP(nid  $n$ , node  $N$ )
3:      $d \leftarrow N.DISTANCE$ 
4:     EMIT(nid  $n$ ,  $N$ ) ▷ Pass along graph structure
5:     for all nodeid  $m \in N.ADJACENCYLIST$  do
6:       EMIT(nid  $m$ ,  $d + 1$ ) ▷ Emit distances to reachable nodes
1: class REDUCER
2:   method REDUCE(nid  $m$ , [ $d_1, d_2, \dots$ ])
3:      $d_{min} \leftarrow \infty$ 
4:      $M \leftarrow \emptyset$ 
5:     for all  $d \in \text{counts } [d_1, d_2, \dots]$  do
6:       if ISNODE( $d$ ) then
7:          $M \leftarrow d$  ▷ Recover graph structure
8:       else if  $d < d_{min}$  then ▷ Look for shorter distance
9:          $d_{min} \leftarrow d$ 
10:     $M.DISTANCE \leftarrow d_{min}$  ▷ Update shortest distance
11:    EMIT(nid  $m$ , node  $M$ )
```

Stopping Criterion

- How many iterations are needed in parallel BFS (equal edge weight case)?
- Convince yourself: when a node is first “discovered”, we’ve found the shortest path
- Now answer the question...
 - Six degrees of separation?
- Practicalities of implementation in MapReduce

Comparison to Dijkstra

- Dijkstra's algorithm is more efficient
 - At any step it only pursues edges from the minimum-cost path inside the frontier
- MapReduce explores all paths in parallel
 - Lots of "waste"
 - Useful work is only done at the "frontier"
- Why can't we do better using MapReduce?

Weighted Edges

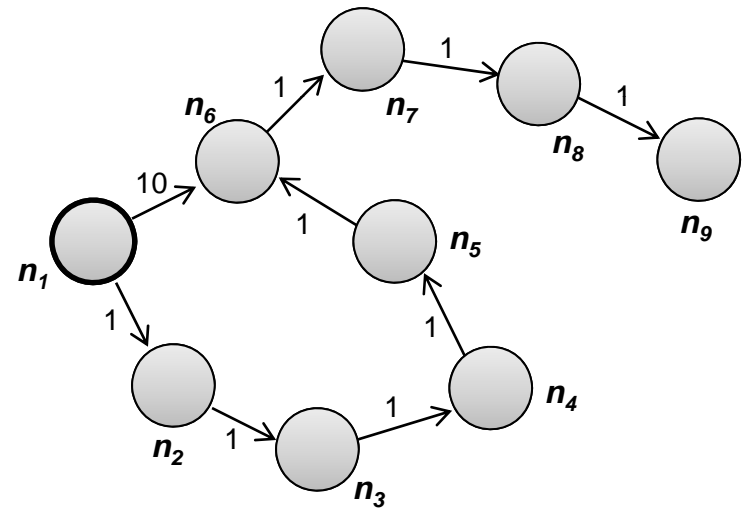
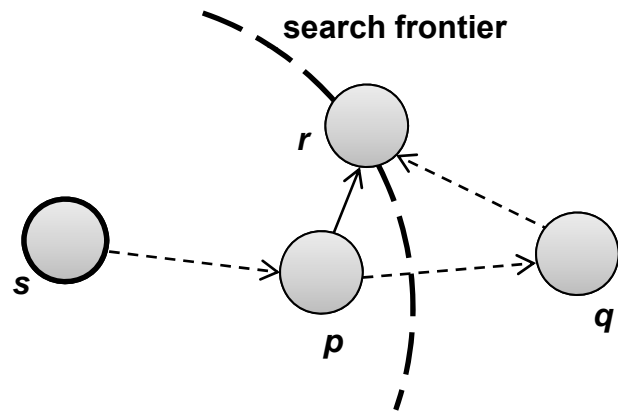
- Now add positive weights to the edges
 - Why can't edge weights be negative?
- Simple change: adjacency list now includes a weight w for each edge
 - In mapper, emit $(m, d + w_p)$ instead of $(m, d + 1)$ for each node m
- That's it?

Stopping Criterion

- How many iterations are needed in parallel BFS (positive edge weight case)?
- Convince yourself: when a node is first “discovered”, we’ve found the shortest path

Not true!

Additional Complexities



Stopping Criterion

- How many iterations are needed in parallel BFS (positive edge weight case)?
- Practicalities of implementation in MapReduce

Graphs and MapReduce

- Graph algorithms typically involve:
 - Performing computations at each node: based on node features, edge features, and local link structure
 - Propagating computations: “traversing” the graph
- Generic recipe:
 - Represent graphs as adjacency lists
 - Perform local computations in mapper
 - Pass along partial results via outlinks, keyed by destination node
 - Perform aggregation in reducer on inlinks to a node
 - Iterate until convergence: controlled by external “driver”
 - Don’t forget to pass the graph structure between iterations

Random Walks Over the Web

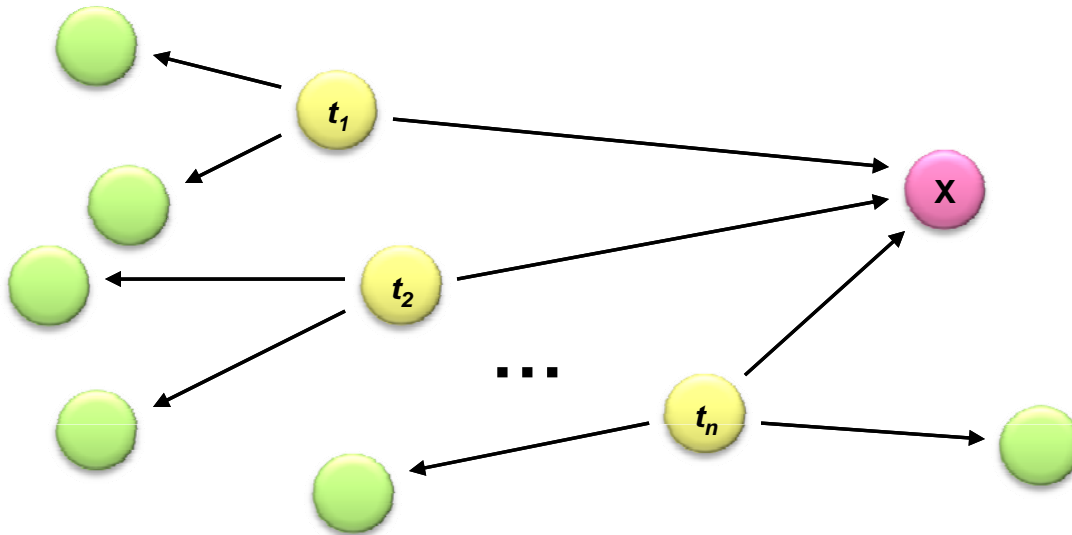
- Random surfer model:
 - User starts at a random Web page
 - User randomly clicks on links, surfing from page to page
- PageRank
 - Characterizes the amount of time spent on any given page
 - Mathematically, a probability distribution over pages
- PageRank captures notions of page importance
 - Correspondence to human intuition?
 - One of thousands of features used in web search
 - Note: query-independent

PageRank: Defined

Given page x with inlinks $t_1 \dots t_n$, where

- $C(t)$ is the out-degree of t
- α is probability of random jump
- N is the total number of nodes in the graph

$$PR(x) = \alpha \left(\frac{1}{N} \right) + (1 - \alpha) \sum_{i=1}^n \frac{PR(t_i)}{C(t_i)}$$



Computing PageRank

- Properties of PageRank

- Can be computed iteratively
- Effects at each iteration are local

- Sketch of algorithm:

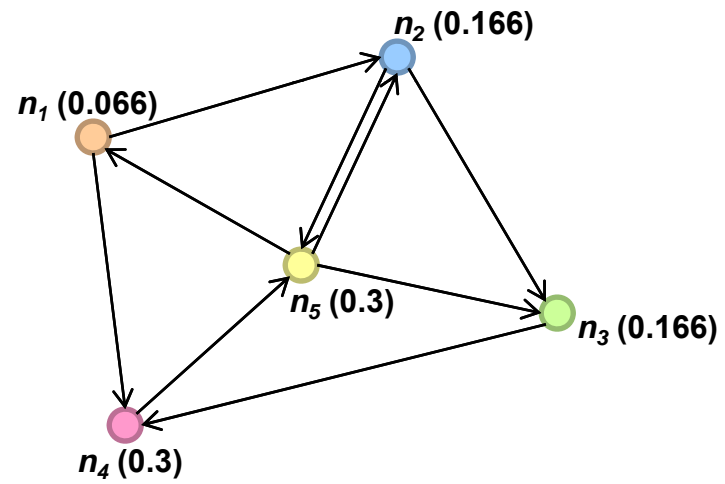
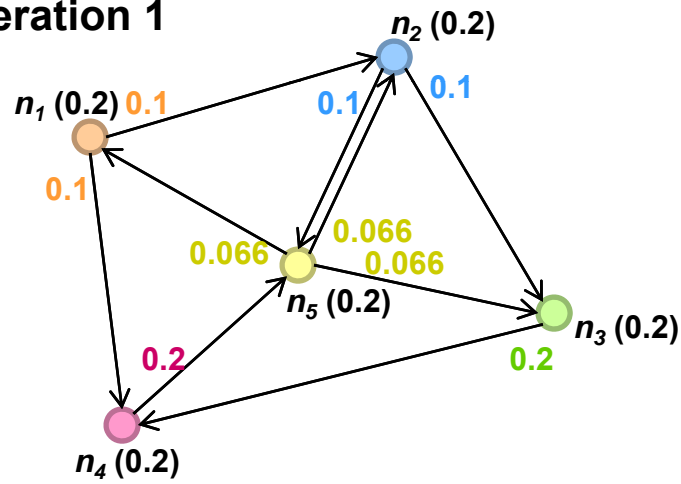
- Start with seed PR_i values
- Each page distributes PR_i “credit” to all pages it links to
- Each target page adds up “credit” from multiple in-bound links to compute PR_{i+1}
- Iterate until values converge

Simplified PageRank

- First, tackle the simple case:
 - No random jump factor
 - No dangling links
- Then, factor in these complexities...
 - Why do we need the random jump?
 - Where do dangling links come from?

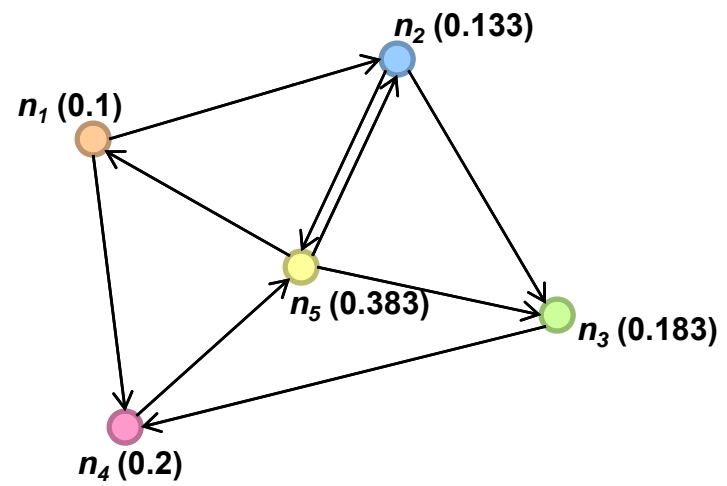
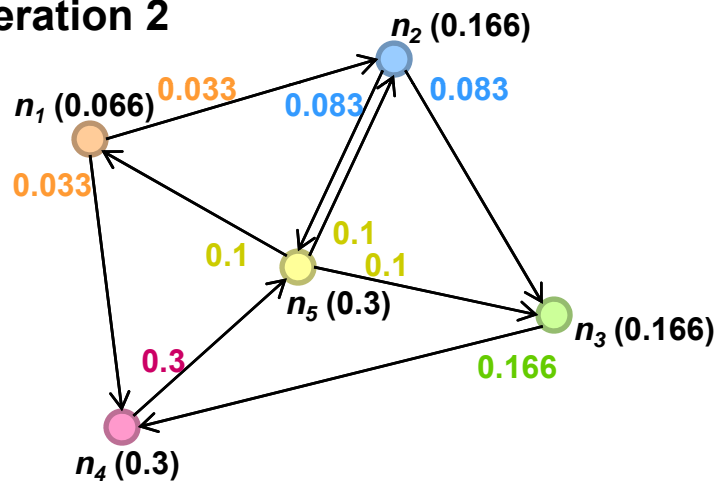
Sample PageRank Iteration (1)

Iteration 1

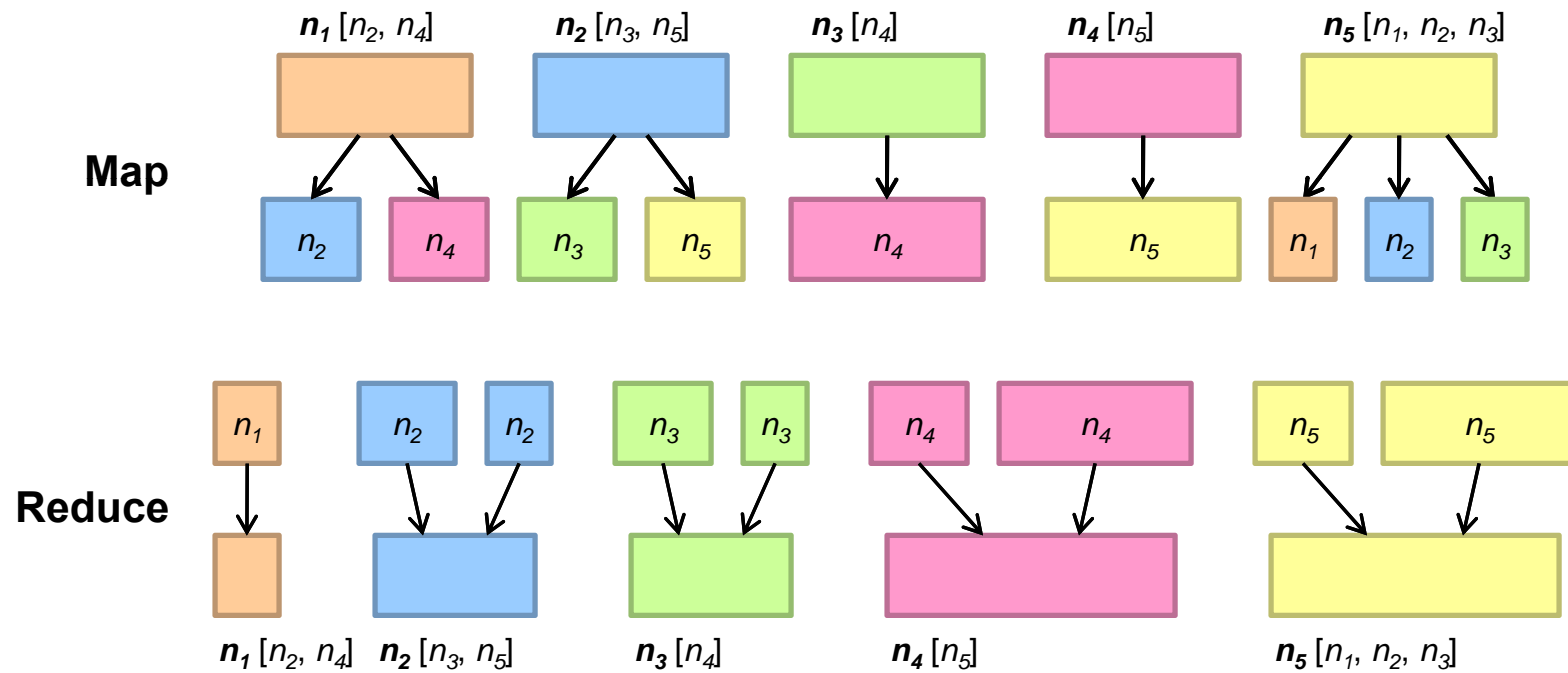


Sample PageRank Iteration (2)

Iteration 2



PageRank in MapReduce



PageRank Pseudo-Code

```
1: class MAPPER
2:   method MAP(nid  $n$ , node  $N$ )
3:      $p \leftarrow N.PAGERANK / |N.ADJACENCYLIST|$ 
4:     EMIT(nid  $n$ ,  $N$ ) ▷ Pass along graph structure
5:     for all nodeid  $m \in N.ADJACENCYLIST$  do
6:       EMIT(nid  $m$ ,  $p$ ) ▷ Pass PageRank mass to neighbors
1: class REDUCER
2:   method REDUCE(nid  $m$ , [ $p_1, p_2, \dots$ ])
3:      $M \leftarrow \emptyset$ 
4:     for all  $p \in$  counts [ $p_1, p_2, \dots$ ] do
5:       if ISNODE( $p$ ) then
6:          $M \leftarrow p$  ▷ Recover graph structure
7:       else
8:          $s \leftarrow s + p$  ▷ Sums incoming PageRank contributions
9:      $M.PAGERANK \leftarrow s$ 
10:    EMIT(nid  $m$ , node  $M$ )
```

Complete PageRank

- Two additional complexities
 - What is the proper treatment of dangling nodes?
 - How do we factor in the random jump factor?
- Solution:
 - Second pass to redistribute “missing PageRank mass” and account for random jumps

$$p' = \alpha \left(\frac{1}{|G|} \right) + (1 - \alpha) \left(\frac{m}{|G|} + p \right)$$

- p is PageRank value from before, p' is updated PageRank value
- $|G|$ is the number of nodes in the graph
- m is the missing PageRank mass

PageRank Convergence

- Alternative convergence criteria
 - Iterate until PageRank values don't change
 - Iterate until PageRank rankings don't change
 - Fixed number of iterations
- Convergence for web graphs?

Beyond PageRank

- Link structure is important for web search
 - PageRank is one of many link-based features: HITS, SALSA, etc.
 - One of many thousands of features used in ranking...
- Adversarial nature of web search
 - Link spamming
 - Spider traps
 - Keyword stuffing
 - ...

Efficient Graph Algorithms

- Sparse vs. dense graphs
- Graph topologies

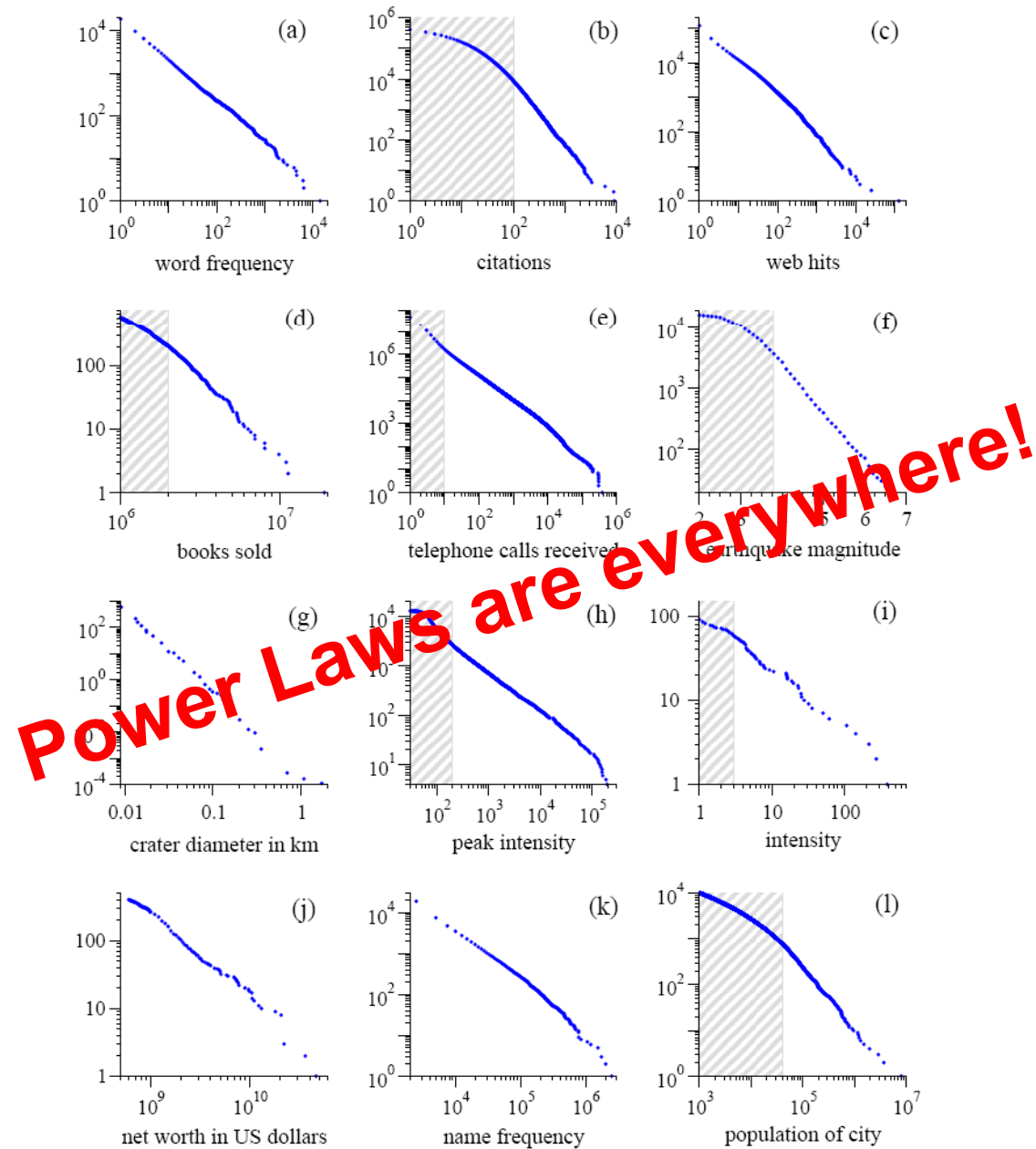


Figure from: Newman, M. E. J. (2005) "Power laws, Pareto distributions and Zipf's law." Contemporary Physics 46:323–351.

Local Aggregation

- Use combiners!
 - In-mapper combining design pattern also applicable
- Maximize opportunities for local aggregation
 - Simple tricks: sorting the dataset in specific ways



Questions?